

INSTALLATION AND OPERATION MANUAL

DORNER Conveyor

Speed Control

Bodine Electric HPP-5137E1 Series
Digital Drive with Analog Interface
NEMA 1 / IP20 (Vented) Enclosure

Dorner P/N 827-100: with direction switch
Dorner P/N 827-101: without direction switch



SEE
SAFETY WARNING
ON [PAGE 2](#)

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(see back cover)

SAFETY WARNING

Definition of Safety Warning Symbols



Electrical Hazard Warning Symbol: Failure to observe this warning could result in electrical shock or electrocution.



Operational Hazard Warning Symbol: Failure to observe this warning could result in serious injury or death.



This product must be installed and serviced by a qualified technician, electrician, or electrical maintenance person familiar with its operation and the hazards involved. Proper installation, which includes electrical connections, fusing or other current protection, and grounding, can reduce the chance of electrical shocks, and/or fires, in this product or products used with this product, such as electric motors, switches, coils, solenoids, and/or relays. Do not use this drive in an explosion-proof application. Eye protection must be worn and insulated adjustment tools must be used when working with drive under power. This product is constructed of materials (plastics, metals, carbon, silicon, etc.) which may be a potential hazard. Proper shielding, grounding, and filtering of this product can reduce the emission of radio frequency interference (RFI) which may adversely affect sensitive electronic equipment. It is the responsibility of the equipment manufacturer and individual installer to supply this Safety Warning to the ultimate end user of this product.

The drive contains electronic Start/Stop circuits, which can be used to start and stop the drive. However, these circuits are never to be used as safety disconnects since they are not fail-safe. Use only the AC Line for this purpose.

Be sure to read and follow all instructions carefully. Fire and/or electrocution can result due to improper use of this product.



This product complies with all CE directives pertinent at the time of manufacture. Contact our Sales Department for Declaration of Conformity. Installation of a CE approved RFI filter is required. Additional shielded cable and/or AC Line cables may be required.

Note: In order for this drive to meet CE requirements, a separate CE approved filter must be installed. Contact Bodine Electric for recommendations on a suitable filter.

UL NOTICE

115 Volt Drives: Suitable for use on a circuit capable of delivering not more than 5 kA RMS symmetrical Amperes. 115 Volts (+/- 15%) maximum. Use copper conductors rated 75 °C minimum. Suitable for operation in a maximum surrounding air temperature of 40 °C.

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LIMITED WARRANTY	Back Cover

1 FAMILIARIZING YOURSELF WITH THE CONTROL

The control has a factory installed On/Off AC Line Switch and a Main Speed Potentiometer. It also may have a Forward-Stop-Reverse Switch, depending on the model number purchased. See [Figure 1](#). Remove the cover to access the drive's jumpers, connectors, and adjustable trimpots. See [Figure 2](#), on [page 6](#).

- **Removing and Installing the Cover:** See [Section 5](#), on [pages 13 and 14](#).
- **Forward-Stop-Reverse Switch:** See [Section 6](#), on [page 15](#).
- **Selectable Jumpers:** See [Section 7](#), on [pages 16 – 19](#).
- **Mounting:** See [Section 8](#), on [page 20](#).
- **Electrical Connections:** See [Section 10](#), on [pages 21 – 23](#).
- **Trim Pot Adjustments:** See [Section 12](#), on [pages 25 – 28](#).
- **Drive Operation:** See [Section 13](#), on [pages 29 and 30](#).
- **Diagnostic Indicators:** See [Section 14](#), on [pages 30 and 31](#).

FIGURE 1
COVER LAYOUT

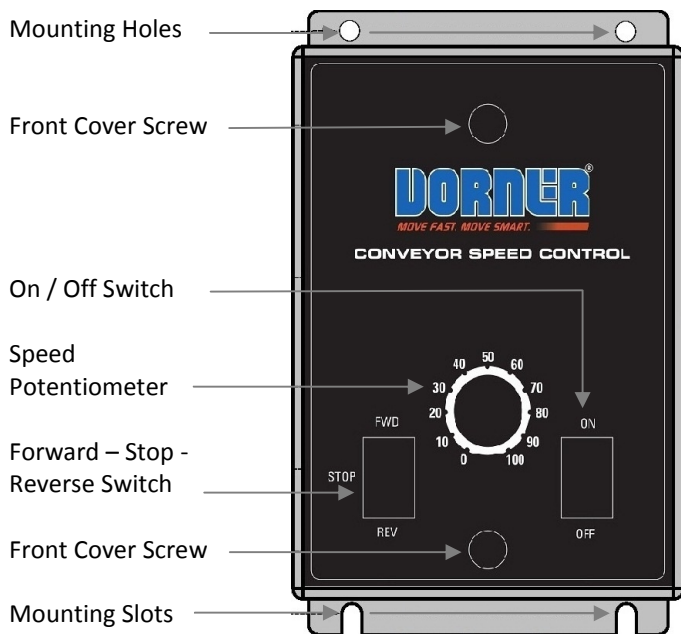
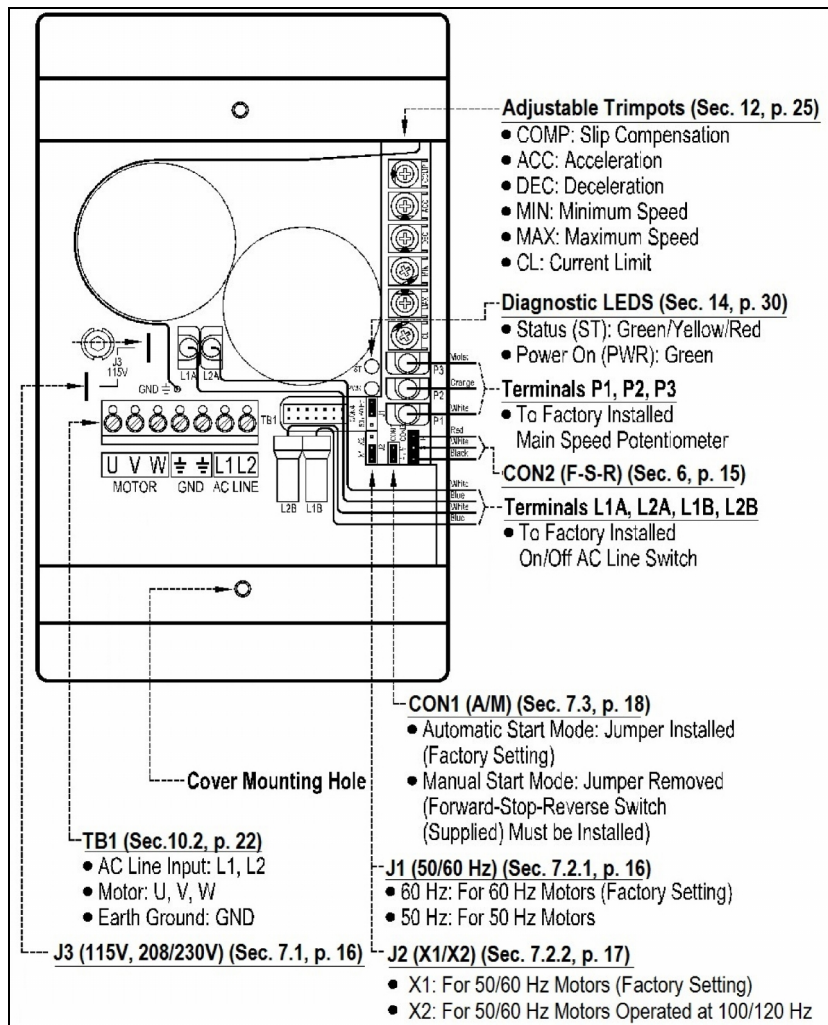


FIGURE 2
DRIVE LAYOUT
(SHOWN WITH COVER REMOVED)



2 ELECTRICAL RATINGS AND SPECIFICATIONS

TABLE 1
ELECTRICAL RATINGS

Maximum Horsepower (HP (kW))	AC Line Input			Fuse or Circuit Breaker Rating (Amps)	Drive Output		Net Wt.	
	Volts AC (50/60 Hz)	Phase (Φ)	Maximum Current (Amps AC)		Maximum Voltage (Volts AC)	Maximum Continuous Load Current (RMS Amps)	lbs	kg
1/2 (0.37)	115	1	9.7	15	230	2.4	1.6	0.72

TABLE 2
GENERAL PERFORMANCE SPECIFICATIONS

Description	Specification	Factory Setting
115 Volt AC Line Input Voltage Operating Range (Volts AC)	115 (±15%)	—
Maximum Load (% Current Overload for 2 Minutes)	150	—
Switching Frequency (kHz)	8	—
Output Frequency Resolution (Bits, Hz)	10, 0.06	—
Minimum Speed Trimpot (MIN) Range (% Frequency Setting)	0 – 40	0
Maximum Speed Trimpot (MAX) Range (% Frequency Setting)	70 – 110	100
Acceleration Trimpot (ACC) Range (Seconds)	0.3 – 20	1.5
Deceleration Trimpot (DEC) Range (Seconds)	0.3 – 20	1.5
Slip Compensation Trimpot (COMP) Range at Drive Rating (Volts/Hz)	0 – 3	1.5
Current Limit Trimpot (CL) Range (% Drive Rating)	60 – 190	160
Motor Frequency Setting (Hz) (Jumper J1)	50, 60	60
Output Frequency Multiplier (X1, X2) (Jumper J2) ¹	1, 2	1
Minimum Operating Frequency at Motor (Hz)	1	—
Speed Range (Ratio)	60:1	—
Speed Regulation (30:1 Speed Range, 0 – Full Load) (% Base Speed) ²	2.5	—
Overload Protection (I ² t) Trip Time for Stalled Motor (Seconds)	6	—
AC Line Input Undervoltage/Overvoltage Trip Points For 115 Volt AC Line (±5%) (Volts AC) ³	76 – 141	—
Operating Temperature Range (°C / °F)	0 – 40 / 32 – 104	—
Operating Humidity Range (% Relative, Non-Condensing)	0 – 95	—
Storage Temperature (°C / °F)	-25 – +85 / -13 – +185	—

Notes: 1. Allows the motor to operate up to two times the rated RPM. Constant horsepower will result when operating the drive in the "X2" Mode. 2. Dependent on motor performance. 3. Do not operate the drive outside the specified AC line input voltage operating range.

3 INTRODUCTION

Thank you for purchasing the DORNER Conveyor Speed Control, a Digital Drive with Analog Interface, housed in a NEMA 1 / IP20 vented enclosure. It is designed to operate subfractional thru 1/2 HP, 208 – 230 Volt, 50 & 60 Hz, 3-phase AC induction motors. Flux Vector Control provides high torque, low noise, and excellent load regulation over a wide speed range. Adjustable Linear Acceleration and Deceleration make the drive suitable for soft-start applications.

Due to its user-friendly design, the drive is easy to install and operate. Tailoring to specific applications is accomplished with selectable jumpers and trimpots, which eliminate the computer-like programming required on other drives. For most applications, no adjustments are necessary.

3.1 STANDARD FEATURES

- **Enclosure:** Housed in a NEMA 1 / IP20 vented enclosure.
- **Cord & Plug for Quick AC Line Connection:** The drive operates from standard 115 Volt 50/60 Hz AC Line input. See [Section 7.1](#), on [page 16](#).
- **Simple to Operate:** Does not require programming. Uses trimpots and jumpers, which are factory set for most applications.
- **Factory Installed On/Off AC Line Switch:** The switch illuminates when power is applied to the drive and the switch is in the on position.
- **Factory Installed Main Speed Potentiometer:** Provides adjustment of motor speed.
- **Factory Installed Forward-Stop-Reverse Switch:** Dorner P/N 827-100 only. Provides manual control of motor operation and direction. See [Section 6](#), on [page 15](#).
- **Diagnostic LEDs:** Power ON (PWR) and drive status (ST). See [Sections 14.2 and 14.3](#), on [page 31](#).
- **Jumper Selection for Drive Output Frequency (Jumpers J1 and J2):** Increases motor speed up to two times the rated RPM. See [Section 7.2](#), on [pages 16 – 17](#).
- **Jumper Selection for Automatic and Manual Start (CON1):** On Dorner P/N 827-101, a jumper is installed so that the drive will automatically start after a fault has been cleared. With the jumper removed, the drive must be manually restarted after a fault has been cleared. On Dorner P/N 827-100, with the Forward-Stop-Reverse Switch, this jumper must remain set for Manual Start. See [Section 7.3](#), on [pages 18 and 19](#).

- **Jumper Selection for Motor Direction (CON2):** Allows selection of Forward or Reverse direction. See [Section 7.4](#), on [page 19](#). On Dorner P/N 827-100, the Forward-Stop-Reverse Switch is factory-connected to this jumper to provide motor reversing and stop, as described in [Section 6](#), on [page 15](#).

3.2 PERFORMANCE FEATURES

- **Power Start™:** Provides more than 200% starting torque which ensures startup of high frictional loads.
- **Flux Vector Control with Static Auto-Tune:** Provides excellent load regulation over a wide speed range.
- **Speed Range:** 60:1

3.3 PROTECTION FEATURES

- **Motor Overload (I²t) with RMS Current Limit:** Provides motor overload protection which prevents motor burnout and eliminates nuisance trips. See [Section 12.6](#), on [page 28](#).
- **Electronic Inrush Current Limit (EICL™):** Eliminates harmful inrush AC line current during startup.
- **Short Circuit:** Prevents drive failure if a short circuit occurs at the motor (phase-to-phase).
- **Regeneration:** Eliminates nuisance tripping due to bus overvoltage caused by rapid deceleration of high inertial loads.
- **Undervoltage and Overvoltage:** Shuts down the drive if the AC line input voltage goes above or below the operating range.
- **MOV Input Transient Suppression.**
- **Microcontroller Self Monitoring and Auto-Reboot.**

3.4 SELECTABLE JUMPERS

- **J1 (50/60 Hz):** Used to set the drive for 60 Hz motors (factory setting) or 50 Hz motors. See [Section 7.2.1](#), on [pages 16 and 17](#).
- **J2 (X1/X2):** Used to set the drive output for twice the motor rated speed (120 Hz (factory setting) or 100 Hz). See [Section 7.2.2](#), on [pages 17 and 18](#).
- **J3 (115V):** The drive is factory set for 115 Volt AC Line input (Jumper J3 installed). For 230 Volt AC Line input, remove Jumper J3. See [Section 7.1](#), on [page 16](#).
- **CON1 (A/M):** Used to set the drive for Automatic or Manual Start Mode. See [Section 7.3](#), on [pages 18 and 19](#).
- **CON2 (Forward/Reverse):** Used to set the drive for forward or reverse speed operation. See [Section 7.4](#), on [page 22](#). On Dorner P/N 827-100, the Forward-Stop-Reverse Switch is connected to this jumper. See [Section 6](#), on [page 15](#).

3.5 ADJUSTABLE TRIMPOTS

- **Minimum Speed (MIN):** Sets the minimum speed of the motor. See [Section 12.1](#), on [page 26](#).
- **Maximum Speed (MAX):** Sets the maximum speed of the motor. See [Section 12.2](#), on [page 26](#).
- **Acceleration (ACC):** Sets the amount of time for the motor to accelerate from zero speed to full speed. See [Section 12.3](#), on [page 26](#).
- **Deceleration (DEC):** Sets the amount of time for the motor to decelerate from full speed to zero speed. See [Section 12.4](#), on [page 27](#).
- **Slip Compensation (COMP):** Used to fine tune the drive for improved load regulation when required by the application. See [Section 12.5](#), on [page 27](#).
- **Current Limit (CL):** Sets the current limit (overload) which limits the maximum current (torque) to the motor. See [Section 12.6](#), on [page 28](#).

4 IMPORTANT APPLICATION INFORMATION

4.1 50 Hz MOTORS

The drive is factory set for 60 Hz motors (Jumper J1 set to the "60 Hz" position). For 50 Hz motors, set Jumper J1 to the "50 Hz" position. Be sure Jumper J2 is set to the "X1" position (factory setting). See [Section 7.2.1](#), on [pages 16 and 17](#).

4.2 MOTOR CURRENT SETTING

The Current Limit (CL) Trimpot is factory set to approximately 160% of the drive's Maximum Continuous Load Current Rating, as shown in [Table 3](#).

In order for the Motor Overload Protection to operate properly for a lower motor rated current, the CL Trimpot will have to be readjusted. **Do not exceed 160% of the drive's Maximum Continuous Load Current Rating.** See [Section 12.6](#), on [page 28](#).

TABLE 3
FACTORY SETTING OF CURRENT LIMIT (CL) TRIMPOT

Drive Rating (Maximum Continuous Load Current) (RMS Amps)	CL Trimpot Setting (Drive Rating X 160%) (RMS Amps)
2.4	3.8

4.3 MOTOR WITH EXTERNAL FAN COOLING

Most totally enclosed fan-cooled (TEFC) and open ventilated 3-phase AC induction motors will overheat if used beyond a limited speed range at full torque. Therefore, it is necessary to reduce motor load as speed is decreased.

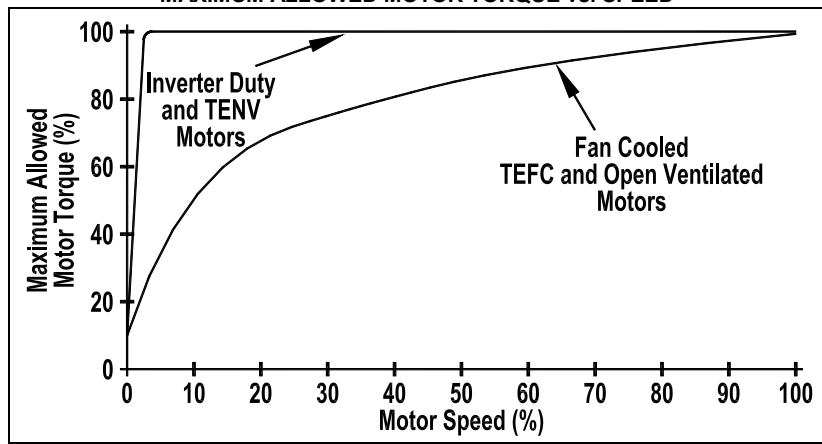
Note: Some fan-cooled motors can be used over a wider speed range. Consult the motor manufacturer for details.

⚠ WARNING! Some motors have low speed characteristics which cause overheating and winding failure under light load or no load conditions. If the motor is operated in this manner for an extended period of time, it is recommended that the unloaded motor current be checked from 1 – 5 Hz (30 – 150 RPM) to ensure motor current does not exceed the nameplate rating. **Do not use motor if the motor current exceeds the nameplate rating.**

⚠ It is recommended that the drive be used with Inverter Duty or TENV motors.

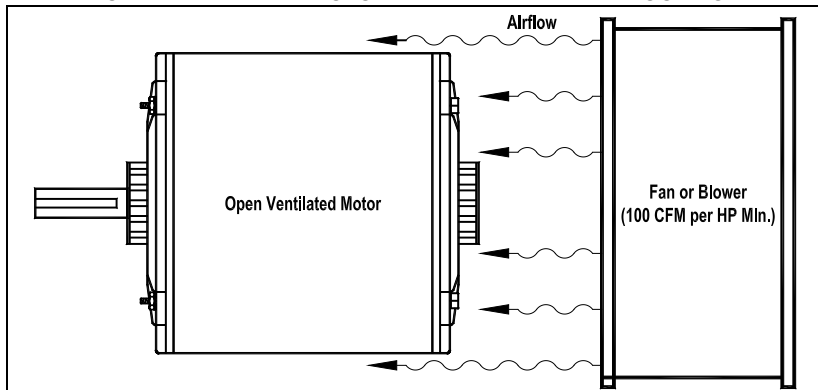
Inverter duty and most totally enclosed non-ventilated (TENV) motors can provide full rated torque over an extended speed range without overheating. See [Figure 3](#).

FIGURE 3
MAXIMUM ALLOWED MOTOR TORQUE vs. SPEED



If external fan cooling is provided, open ventilated motors can also achieve an extended speed range at full rated torque. A box fan or blower with a minimum of 100 CFM per HP is recommended. Mount the fan or blower so the motor is surrounded by the airflow. See [Figure 4](#).

FIGURE 4
OPEN VENTILATED MOTOR WITH EXTERNAL FAN COOLING



4.4 ELECTRONIC MOTOR OVERLOAD PROTECTION

The drive contains Modified I^2t Overload Protection. Part of this function consists of a Current Limit (CL) circuit, which limits the drive current to a factory preset level of 160% of the rated drive current. The CL Trimpot is used to recalibrate the drive current from 60% thru 190%. The Power Start™ circuit provides an overshoot function that allows most motors to develop more than 200% of starting torque and breakdown torque.

Standard I^2t is undesirable because it causes nuisance tripping. It allows a very high motor current to develop and will turn the drive off after a very short period of time. The RMS Current Limit Circuit avoids this nuisance tripping while providing maximum motor protection.

If the motor is overloaded to 120% of full load (75% of the CL setting), the I^2t Timer starts. If the motor continues to be overloaded at the 120% level, the timer will shut down the drive after 30 minutes. If the motor is overloaded to 160% of full load, the drive will trip in 6 seconds.

5 REMOVING AND INSTALLING THE COVER

The cover must be removed to change any of the internal factory settings. See [Section 5.1, below](#), for instructions on removing the cover. See [Section 5.2](#), on [page 17](#), for instructions on installing the cover.

- **Jumper Settings:** See [Section 7](#), on [pages 16 – 19](#).
- **AC Line, Motor, and Ground Connections:** See [Sections 10](#), on [pages 21 – 23](#).
- **Trimpot Adjustments:** See [Section 12](#), on [pages 25 – 28](#).



WARNING! Disconnect the main power before removing or installing the cover.



WARNING! After disconnecting the main power to the drive, wait at least 30 seconds before removing the cover.



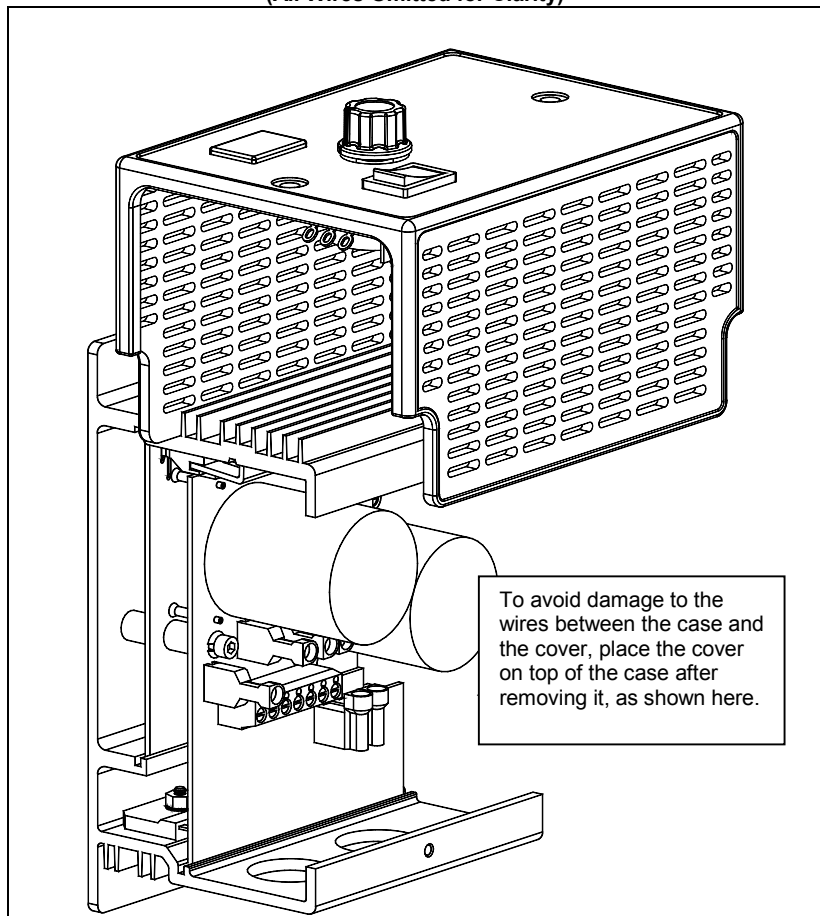
WARNING! To prevent accidental contact with high voltage, it is required that the cover be properly installed onto the drive after all wiring and setup is complete. It offers protection against electric shock which limits the potential liability to the equipment manufacturer and installer.

5.1 REMOVING THE COVER

Remove the two screws on the cover and slide it off the drive's base. Be careful not to separate the wires from the drive to the cover's On/Off AC Line Switch, Main Speed Potentiometer, and Forward-Stop-Reverse Switch.

To avoid damage to the wires from the drive to the cover, place the cover on top of the case after removing it, as shown in [Figure 5](#), on [page 14](#).

FIGURE 5
COVER POSITIONED ON TOP OF CASE
(All Wires Omitted for Clarity)



5.2 INSTALLING THE COVER

After setting up the drive, install the cover. Be sure that the wires remain inside the drive so they do not get crimped while it is being installed. Replace the two cover screws. The screws should be tightened to 5 in-lbs (5.76 kg-cm) – do not overtighten.

6 INSTALLING A FORWARD-STOP-REVERSE SWITCH

Dorner P/N 827-100 comes with a Forward-Stop-Reverse Switch. Dorner P/N 827-101 does not, but one can be added later if necessary, after obtaining the necessary parts. The switch assembly easily installs onto the cover. Follow steps 1 – 10, [below](#), and see [Figure 6](#).



WARNING! Disconnect the main power before installing the Forward-Stop-Reverse Switch.

Installing the Forward-Stop-Reverse Switch

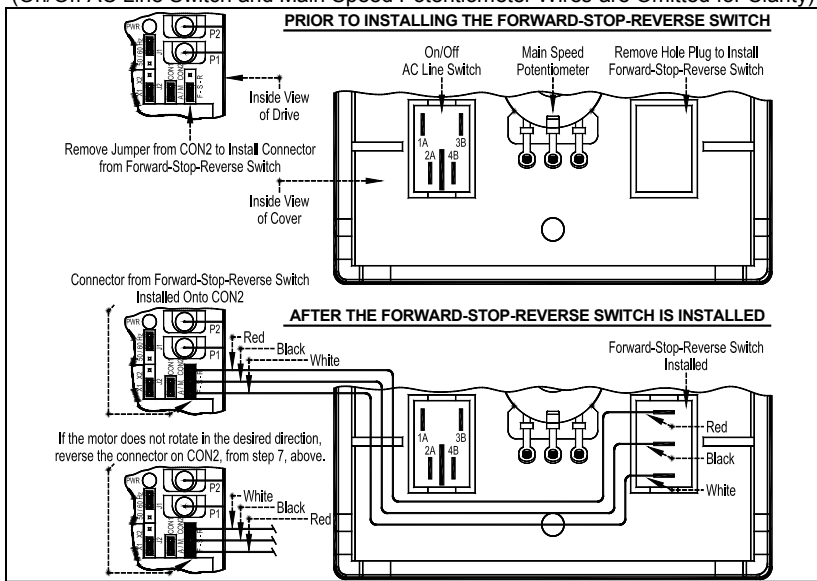
1. Remove the cover, as described in [Section 5.1](#), on [pages 13 and 14](#).
2. Remove the hole plug from the cover.
3. Remove the jumper from CON2 (F-S-R).
4. Feed the connector with the switch wires through the cover.
5. Orient the switch (red wire toward "FWD" and white wire toward "REV").
6. Push the switch through the cover hole until it snap-mounts into position.
7. Orient the connector (red wire to "R" pin and white wire to "F" pin).*
8. Install the connector onto CON2 on the drive.
9. Use the two wire ties (supplied) to secure the switch wires to the existing wires. The wire ties should be placed next to the existing wire ties.
10. Replace the cover, as described in [Section 5.2](#), on [page 14](#).

**If the motor does not rotate in the desired direction, reverse the connector on CON2, from step 7, above (with the AC Line disconnected and the motor stopped).*

FIGURE 6

FORWARD-STOP-REVERSE SWITCH INSTALLATION

(On/Off AC Line Switch and Main Speed Potentiometer Wires are Omitted for Clarity)



7 SETTING SELECTABLE JUMPERS

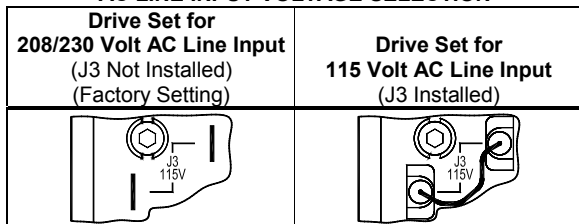
The drive has selectable jumpers which must be set before the drive can be used. For the location of jumpers, see [Figure 2](#), on [page 6](#).

7.1 AC LINE INPUT VOLTAGE SELECTION (JUMPER J3)

The drive is factory set for 115 Volt AC Line input (Jumper J3 installed). For 230 Volt AC line input, remove Jumper J3 from the two PC board quick-connect terminals. See [Figure 7](#). Note that the factory-supplied line cord & plug is only appropriate for 115 Volt AC and must be replaced or modified for a 230 Volt AC line.

Note: 230 Volts AC will be applied to the motor with 115 Volt AC line input.

FIGURE 7
AC LINE INPUT VOLTAGE SELECTION




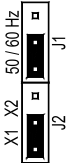
7.2 60 Hz AND 50 Hz MOTOR OPERATION AND DRIVE OUTPUT FREQUENCY SELECTION (JUMPERS J1 AND J2)

Both Jumpers J1 and J2 must be set for the appropriate motor nameplate frequency rating.

7.2.1 SETTING THE DRIVE FOR 60 Hz OR 50 Hz MOTOR OPERATION

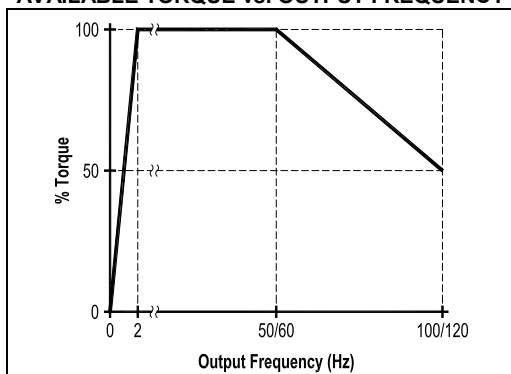
The drive is factory set to operate 60 Hz motors. Jumper J1 is factory set to the "60 Hz" position and Jumper J2 is factory set to the "X1" position. For 50 Hz motors, set Jumper J1 to the "50 Hz" position, and be sure Jumper J2 is set to the "X1" position. See [Figure 8](#), on [page 17](#).

FIGURE 8**60 Hz AND 50 Hz MOTOR SELECTION**

60 Hz Motor Operation (Factory Setting) (J1 Installed in "60 Hz" Position) (J2 Installed in "X1" Position)	50 Hz Motor Operation (J1 Installed in "50 Hz" Position) (J2 Installed in "X1" Position)
	

7.2.2 SETTING THE DRIVE FOR TWO TIMES THE RATED MOTOR RPM

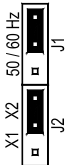

The drive can also be used to operate the motor up to two times the rated RPM. However, constant horsepower will result when operating the drive in the "X2" Mode. See [Figure 9](#).

FIGURE 9**AVAILABLE TORQUE vs. OUTPUT FREQUENCY**

For 120 Hz output with 60 Hz motor, be sure Jumper J1 is set to the "60 Hz" position and set Jumper J2 to the "X2" position. For 100 Hz output with 50 Hz motor, set Jumper J1 to the "50 Hz" position and set Jumper J2 to the "X2" position. See [Figure 10](#).

FIGURE 10

120 Hz AND 100 Hz DRIVE OUTPUT FREQUENCY SELECTION

120 Hz Output with 60 Hz Motor (J1 Installed in "60 Hz" Position) (J2 Installed in "X2" Position)	100 Hz Output with 50 Hz Motor (J1 Installed in "50 Hz" Position) (J2 Installed in "X2" Position)
	

7.3 AUTOMATIC AND MANUAL START MODE (CON1)

CON1 is used to set the drive for Automatic or Manual Start Mode.

7.3.1 AUTOMATIC START MODE

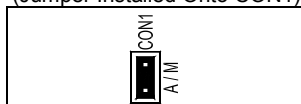
DORNER P/N 827-101 is factory set for Automatic Start Mode (jumper installed onto CON1). See [Figure 11](#).

The drive will automatically start when power is applied. The drive will also automatically restart after a recovered fault due to undervoltage or overvoltage. After two Short Circuit Faults (at the motor), the drive must be restarted using the AC Line Switch. For an Overload Trip, due to a prolonged overload, the drive must be manually restarted using the AC Line Switch or the Forward-Stop-Reverse Switch, if installed.

FIGURE 11

AUTOMATIC START

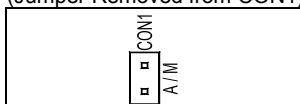
(Jumper Installed Onto CON1)



7.3.2 MANUAL START MODE

DORNER P/N 827-100 is factory set for Manual Start Mode (jumper removed from CON1). See Figure 12. The Manual Start Mode is used to manually start the drive or restart the drive (reset) if a fault has occurred.

FIGURE 12
MANUAL START
(Jumper Removed from CON1)



In the Manual Start Mode, the drive will trip due to all faults (Overvoltage, Undervoltage, Short Circuit, and Overload Trip) and remain tripped even when the fault is cleared.

To reset the drive after a fault has cleared, set the Forward-Stop-Reverse Switch to the "STOP" position and then to the desired direction. Also, the drive must be restarted each time the AC line is interrupted. To reset the drive after a Short Circuit Fault has cleared, use the AC Line Switch.

7.4 FORWARD / REVERSE SPEED SELECTION (CON2)

DORNER P/N 827-101 is factory set for Forward Speed Operation (jumper installed in the "F" position of CON2). For reverse Speed Operation, install the jumper in the "R" position. See Figure 13. If the application requires that the direction be changed repeatedly, DORNER P/N 827-100 should be used instead.

Note: As an alternate to using the F-S-R jumper, reverse any two motor leads (with the AC Line disconnected and the motor stopped).

FIGURE 13
FORWARD / REVERSE SPEED SELECTION

Forward Speed Operation (Jumper Installed in "F" Position) (Factory Setting)	Reverse Speed Operation (Jumper Installed in "R" Position)
A diagram of a terminal block labeled CON2. It has two positions: a top position with a small square symbol and a bottom position labeled 'F-S-R'. The top position is empty, and the bottom position has a small square symbol, indicating the jumper is installed in the 'F' position.	A diagram of a terminal block labeled CON2. It has two positions: a top position with a small square symbol and a bottom position labeled 'F-S-R'. The top position has a small square symbol, and the bottom position is empty, indicating the jumper is installed in the 'R' position.

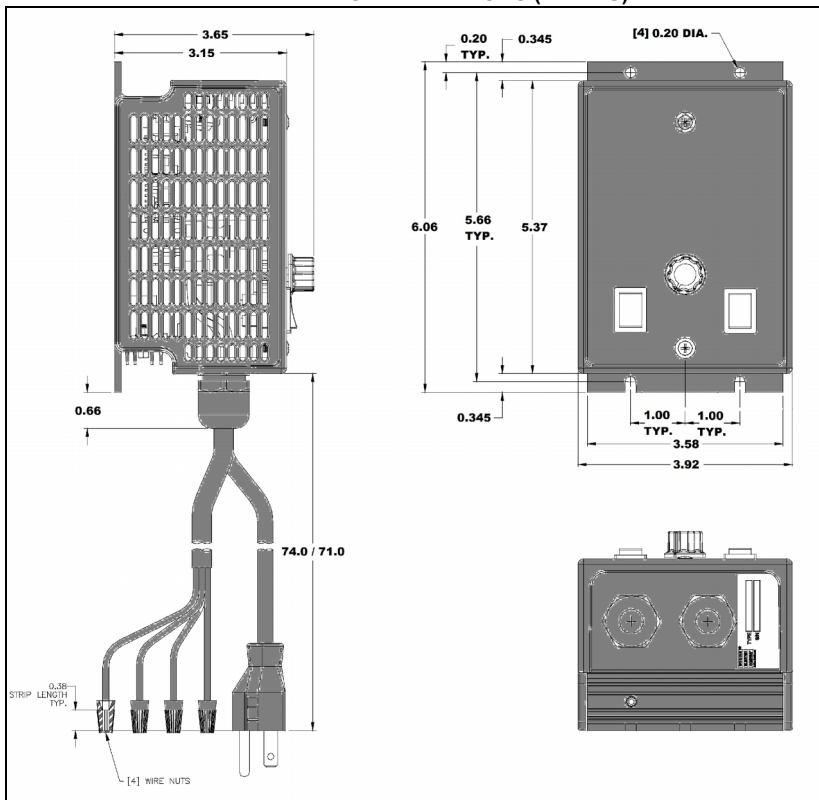
8 MOUNTING

It is recommended that the drive be mounted vertically on a flat surface with adequate ventilation. Leave enough room below the drive to allow for AC Line, motor connections, and any other connections that are required. Care should be taken to avoid extreme hazardous locations where physical damage can occur. When mounting the drive in an enclosure, the enclosure should be large enough to allow proper heat dissipation so that the ambient temperature does not exceed 40 °C (104 °F) at full rating. See [Figure 14](#).



WARNING! DO NOT USE THIS DRIVE IN AN EXPLOSIVE ENVIRONMENT. AN EXPLOSION CAN CAUSE SERIOUS OR FATAL INJURY. THIS DRIVE IS NOT EXPLOSION PROOF.

FIGURE 14
MECHANICAL SPECIFICATIONS (INCHES)




9 RECONDITIONING THE BUS CAPACITORS

This drive contains bus capacitors which must be reconditioned if the drive has been in storage for over one year. To recondition the capacitors, apply the AC Line for a minimum of one hour, with the Main Speed Potentiometer set to zero, or set the Forward-Stop-Reverse Switch, if installed, to the Stop position.

10 ELECTRICAL CONNECTIONS

The basic drive is designed with a PC board mounted terminal block to facilitate wiring of the AC Line input, Motor, and Ground connections, as shown in [Figure 2](#), on [page 6](#). The DORNER models come with a line cord & plug factory installed. The removable cover allows access to the terminal block, jumpers, and trimpots for wiring and setting up the drive. For Terminal Block TB1 Wire and Tightening Torque Specifications, see [Table 4 below](#).

Note: Wire the control in accordance with the National Electrical Code requirements and other local codes that may apply to the application.

 **WARNING! HIGH VOLTAGE!** Read [Safety Warning](#), on [page 2](#), before using the drive. Disconnect the main power before making connections to the drive. To avoid electric shock, be sure to properly ground the drive.

Application Notes: 1. To avoid erratic operation, do not bundle AC Line input and motor wires with each other. Also, do not bundle motor wires from multiple drives in the same conduit. 2. Be sure to properly fuse each AC Line conductor that is not at ground potential. Do not fuse neutral or grounded conductors. A separate AC Line switch or contactor must be used as a disconnect so that each ungrounded conductor is opened. For fuse or circuit breaker selection, see [Table 1](#), on [page 7](#). Also see [Section 10.3](#), on [page 23](#).

TABLE 4
TERMINAL BLOCK TB1
WIRE AND TIGHTENING TORQUE SPECIFICATIONS

Copper Wire Size Range (Solid or Stranded*)		Stripping Length		Tightening Torque Range	
AWG	mm ²	in	mm	in-lbs	kg-cm
30 – 14	0.05 – 2.08	0.25	6	4.4 – 5.3	5.1 – 6.1

*If using stranded wire, be sure that all strands are contained in the terminal block housing.

10.1 AC LINE INPUT AND GROUND

The DORNER controls come with a line cord & plug factory installed. These instructions are provided in case that cord needs to be replaced for some reason (like operation from a 230 Volt AC line). Connect the single-phase AC line input to TB1 Terminals "L1" and "L2". Connect the Ground (earth) to TB1 Terminal "GND". See [Figure 15](#), on [page 23](#). **For 208/230 Volt AC Line input, be sure that Jumper J3 is not installed. For 115 Volt AC Line input, install Jumper J3 (supplied). See Section 7.1, on page 16.**

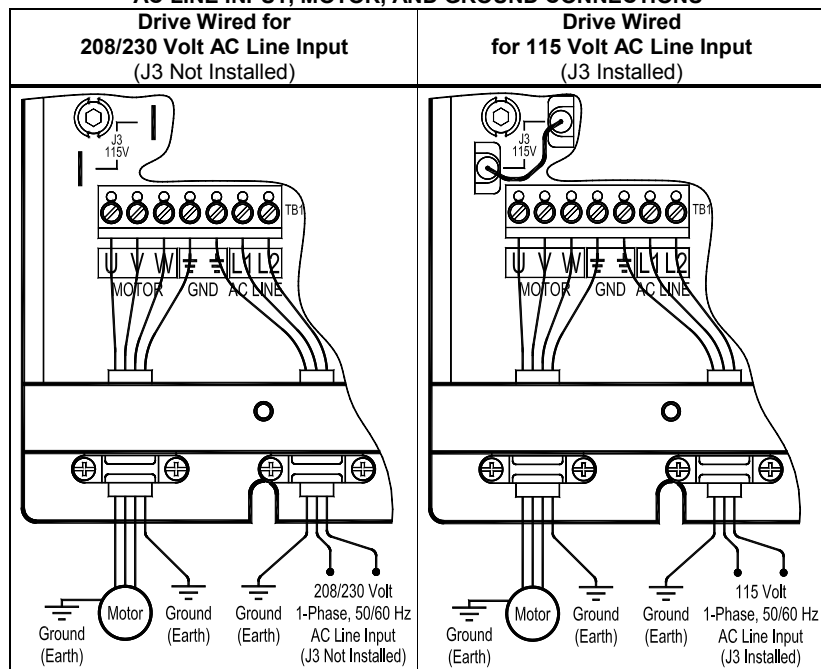
10.2 MOTOR AND GROUND

The DORNER controls come with a motor cord factory installed. These instructions are provided in case that cord needs to be replaced for some reason (like a different length). Connect the Motor to TB1 Terminals "U", "V", and "W". Connect the Ground (earth) to TB1 Terminal "GND". See [Figure 15](#), on [page 23](#).

Motor cable length should not exceed 100 feet (30 m) – special reactors may be required – consult our Sales Department.

Be sure that the Current Limit is calibrated to the actual motor nameplate current rating. Do not exceed the drive's maximum current rating.

Note: *If the motor does not rotate in the desired direction, either: 1. Reverse any two motor leads (with the AC Line disconnected and the motor stopped). 2. Change the setting of the F-S-R Jumper, on CON2. See [Section 7.4](#), on [page 19](#). 3. If the Forward-Stop-Reverse Switch is installed, reverse the connector installed on CON2. See [Section 6](#), on [page 15](#).*

FIGURE 15**AC LINE INPUT, MOTOR, AND GROUND CONNECTIONS****10.3 AC LINE INPUT FUSING**

The drive does not contain AC Line fuses. For the recommended fuse or circuit breaker rating, see [Table 1](#), on [page 7](#). Do not fuse motor leads. Most electrical codes require that each ungrounded conductor contain circuit protection. Do not fuse neutral or ground connections. It is recommended to install a fuse (Littelfuse 326, Buss ABC, or equivalent) or a circuit breaker (Square D QOU or equivalent) in series with each ungrounded conductor.

11 HIGH VOLTAGE DIELECTRIC WITHSTAND TEST (HI-POT TEST)

DESCRIPTION

Testing agencies such as UL, CSA, etc., usually require that equipment undergo an AC Hi-Pot Test. In order to prevent catastrophic damage to the drive, which has been installed in the equipment, the following procedure is recommended. A typical Hi-Pot Test Setup is shown in [Figure 16](#), on [page 25](#).

All drives have been factory hi-pot tested in accordance with UL requirements.

DC Hi-Pot Test Voltage = ((Line Voltage X 2) + 1000) X 1.41

TABLE 5

DC HI-POT TESTER SETUP INFORMATION

Input Line Voltage (Volts AC)	Hi-Pot Test Voltage (Volts DC)
115	1800
208/230	2100

EQUIPMENT

A ramp-up type AC Hi-Pot Tester must be used. A suggested Hi-Pot Tester is Slaughter Model 2550, or equivalent.

Note: *If the Hi-Pot Tester does not have automatic ramping, then the hi-pot output must be manually increased to the test voltage and then manually reduced to zero.*

PROCEDURE

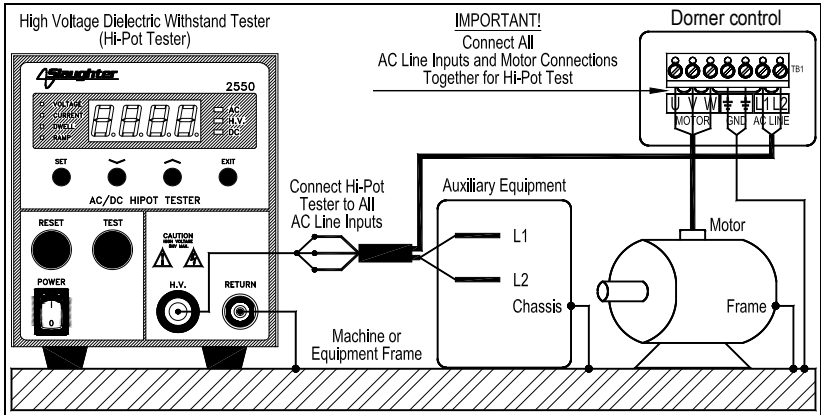


Warning! All equipment AC line inputs must be disconnected from the AC power before performing the Hi-Pot Test.

1. Set the Hi-pot Tester to the appropriate voltage, as shown in [Table 5](#), above.
2. Connect all equipment AC power input lines together and connect them to the H.V. lead of the Hi-Pot Tester.
3. Connect the RETURN of the Hi-Pot Tester to the frame on which the drive and other auxiliary equipment are mounted. The Hi-Pot Tester must have an automatic ramp-up to the test voltage and an automatic ramp-down to zero voltage.

CAUTION! Instantly applying the hi-pot voltage (versus ramping up/down) will cause irreversible damage to the drive, which will void the warranty.

FIGURE 16
TYPICAL HI-POT TEST SETUP



12 TRIMPOT ADJUSTMENTS

The drive contains trim pots which are factory set for most applications. See [Figure 2](#), on [page 6](#), for the location of the trim pots and their approximate factory calibrated positions. Some applications may require readjustment of the trim pots in order to tailor the drive for a specific requirement. The trim pots may be readjusted as follows.



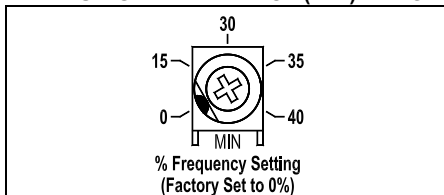
WARNING! If possible, do not adjust trim pots with the main power applied. If adjustments are made with the main power applied, an insulated adjustment tool must be used and safety glasses must be worn. High voltage exists in this drive. Fire and/or electrocution can result if caution is not exercised. [Safety Warning](#), on [page 2](#), must be read and understood before proceeding.

12.1 MINIMUM SPEED TRIM POT (MIN)

Sets the minimum speed of the motor. The MIN Trim pot is factory set to 0% of frequency setting.

For a higher minimum speed setting, rotate the MIN Trim pot clockwise. See Figure 17.

FIGURE 17
MINIMUM SPEED TRIM POT (MIN) RANGE

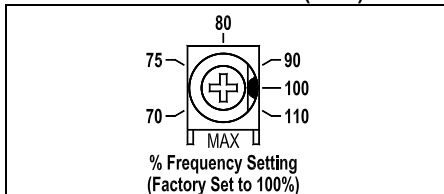


12.2 MAXIMUM SPEED TRIM POT (MAX)

Sets the maximum speed of the motor. The MAX Trim pot is factory set to 100% of frequency setting.

For a higher maximum speed setting, rotate the MAX Trim pot clockwise. For a lower maximum speed setting, rotate the MAX Trim pot counterclockwise. See Figure 18.

FIGURE 18
MAXIMUM SPEED TRIM POT (MAX) RANGE

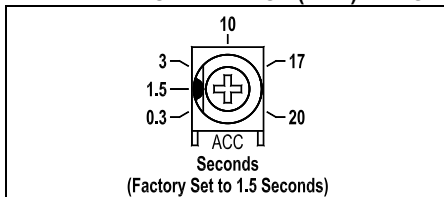


12.3 ACCELERATION TRIM POT (ACC)

Sets the amount of time for the motor to accelerate from zero speed to full speed. The ACC Trim pot is factory set to 1.5 seconds.

For longer acceleration time, rotate the ACC Trim pot clockwise. For more rapid acceleration, rotate the ACC Trim pot counterclockwise. See Figure 19.

FIGURE 19
ACCELERATION TRIM POT (ACC) RANGE



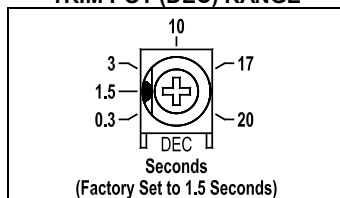
Note: Rapid acceleration settings may cause the current limit circuit to activate, which will extend the acceleration time.

12.4 DECELERATION TRIM POT (DEC)

Sets the amount of time for the motor to decelerate from full speed to zero speed. The DEC Trim pot is factory set to 1.5 seconds.

For longer deceleration time, rotate the DEC Trim pot clockwise. For more rapid deceleration, rotate the DEC Trim pot counterclockwise. See Figure 20.

FIGURE 20
DECELERATION
TRIM POT (DEC) RANGE



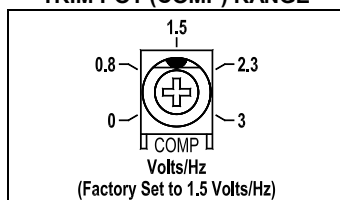
Application Note: On applications with high inertial loads, the deceleration may automatically increase in time. This will slow down the rate of speed of decrease to prevent the bus voltage from rising to the Overvoltage Trip point. This function is called Regeneration Protection. **It is recommended that for very high inertial loads that both the ACC and DEC Trim pots should be set to greater than 10 seconds.**

12.5 SLIP COMPENSATION TRIM POT (COMP)

Sets the amount of Volts/Hz to maintain set motor speed under varying loads. Used to fine tune the drive for improved load regulation. The COMP Trim pot is factory set to 1.5 Volts/Hz, which provides excellent speed regulation for most motors.

To increase the slip compensation, rotate the COMP Trim pot clockwise.* To decrease the slip compensation, rotate the COMP Trim pot counterclockwise. See Figure 21.

FIGURE 21
SLIP COMPENSATION
TRIM POT (COMP) RANGE



***Note:** Increasing the Slip Compensation beyond what is required may cause unstable motor operation.

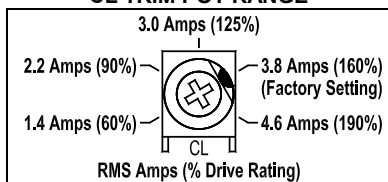
12.6 CURRENT LIMIT TRIM POT (CL)

Motor Overload (I^2t) with RMS Current Limit (CL) sets the current limit (overload), which limits the maximum current to the motor, prevents motor burnout, and eliminates nuisance trips. In order to ensure that the motor is properly protected with the I^2t feature, it is required that the CL Trim pot be set for 160% of the motor nameplate rating.

The CL Trim pot is factory set to 160% of the drive's Maximum Continuous Load Current rating. To increase the current limit, rotate the CL Trim pot clockwise. To decrease the current limit, rotate the CL Trim pot counterclockwise. See [Figures 22](#).

Note: During normal operation, if the ST LED illuminates red, the CL Trim pot may be set too low or the motor may be overloaded. Either increase the CL Trim pot setting or monitor the motor current to adjust the CL Trim pot for the proper setting.

FIGURE 22
CL TRIM POT RANGE



13 DRIVE OPERATION

13.1 START-UP PROCEDURE

After the drive has been properly setup (jumpers and trim pots set to the desired positions) and wiring completed, the startup procedure can begin.



WARNING! The motor will run at the Main Speed Potentiometer setting when the AC Line is applied to the drive and the On/Off AC Line Switch is set to the on position.

To start the drive, set the On/Off AC Line Switch to the "ON" position. If the AC power has been properly brought to the drive, the On/Off AC Line Switch will illuminate. If the control has a Forward-Stop-Reverse Switch, set it to either the "FORWARD" or "REVERSE" position. The motor will begin to accelerate according to the Main Speed Potentiometer setting.

If the Cover Is Removed: Observe that the PC board mounted Power On LED (PWR) illuminates green. The PC board mounted Status LED (ST) will indicate the drive status, as described in [Section 14.3](#), on [page 31](#).

Note: If the motor does not rotate in the desired direction, either: **1.** Reverse any two motor leads (with the AC Line disconnected and the motor stopped). **2.** Change the setting of the F-S-R Jumper, on CON2. See [Section 7.4](#), on [page 19](#). **3.** If the Forward-Stop-Reverse Switch is installed, reverse the connector installed on CON2. See [Section 6](#), on [page 15](#).

13.2 FAULT RECOVERY

The drive monitors four faults (Undervoltage, Overvoltage, Short Circuit (at the motor (phase-to-phase)), and Motor Overload). [Table 6](#), on [page 30](#), describes how the drive will recover after the fault has cleared. For an Overload Trip, see [Section 13.3](#), on [page 30](#).

Application Note: In Manual Start Mode (the control must have a Forward-Stop-Reverse Switch); the drive must be manually reset for any fault. Set the Forward-Stop-Reverse Switch to the "STOP" position and then to the desired direction setting. See [Section 6](#), on [page 15](#).

TABLE 6
FAULT RECOVERY AND RESETTING THE DRIVE*
(In Automatic Start Mode (Jumper Installed Onto CON1))

Fault	Drive Recovery
Undervoltage	Drive will automatically start after the bus voltage returns to the operational level or when the drive is first turned on (power up).
Overvoltage	Drive will automatically start after the bus voltage returns to the operational level.
Short Circuit	After two faults, the drive must be restarted using the AC line.
Motor Overload (I^2t)	Drive must be manually restarted. See Section 13.3 , below.

**The fault must be cleared before the drive can be reset.*

13.3 RESTARTING THE DRIVE AFTER AN OVERLOAD FAULT HAS CLEARED

The drive can be restarted after an Overload Fault has cleared by any of the following two methods.

Note: If an Overload Trip occurs, the motor may be overloaded. Check the motor current with an AC RMS responding ammeter. Also, the CL setting may be set too low. See [Section 12.6](#), on [page 28](#).

1. Use the On/Off AC Line Switch to turn the power off and on (approximately 15 seconds). If the cover is opened, observe that the Status LED (ST) changes from quick flashing red to flashing red/yellow.
2. Set the Forward-Stop-Reverse Switch, if installed, to the "STOP" position and then to the desired direction setting.

14 DIAGNOSTIC INDICATORS

The drive contains an illuminated On/Off AC Line Switch and two diagnostic LEDs to display the drive's operational status. See [Figure 2](#), on [page 6](#), for the location of the "PWR" and "ST" LEDs.

Note: *Dorner P/N 827-101 is factory set to the Automatic Start Mode. Dorner P/N 827-100 is factory set for Manual Start/Reset Mode, see [Section 7.3.2](#), on [page 19](#).*

14.1 ILLUMINATED ON/OFF AC LINE SWITCH

The On/Off AC Line Switch will illuminate when the AC line is applied to the drive and the switch is in the ON ("I") position.

14.2 POWER ON LED (PWR)

The "PWR" LED, located on the drive's PC board, will illuminate green when the AC line is applied to the drive and the On/Off AC Line Switch is set to the on ("I") position.

14.3 STATUS LED (ST)

The "ST" LED, located on the drive's PC board, is a tricolor LED which provides indication of a fault or abnormal condition. The information provided can be used to diagnose an installation problem such as incorrect input voltage, overload condition, and drive output miswiring. It also provides a signal which informs the user that all drive and microcontroller operating parameters are normal. [Table 7](#), summarizes the "ST" LED functions.

TABLE 7
OPERATING CONDITION AND STATUS LED INDICATOR

Operating Condition	Status LED	
	Flash Rate ¹	Color
Normal Operation	Slow	Green
Overload (120% - 160% Full Load)	Steady	Red ²
Overload Trip (Drive Timed Out)	Quick	Red ²
Short Circuit	Slow	Red
Undervoltage	Quick	Red/Yellow
Undervoltage Recovery ³	Quick	Red/Yellow/Green
Overvoltage	Slow	Red/Yellow
Overvoltage Recovery ³	Slow	Red/Yellow/Green
Stop	Steady	Yellow

Notes: 1. Slow Flash = 1 second on and 1 second off. Quick Flash = 0.25 second on and 0.25 second off. 2. In Manual Start Mode, when the Overload is removed, before the I^2t times out and trips the drive, the Status LED will flash green. 3. In Manual Start Mode, when the Undervoltage or Overvoltage condition is corrected, the Status LED will flash Red/Yellow/Green.

LIMITED WARRANTY

The Bodine Electric Company warrants all products it manufactures to be free of defects in workmanship and materials when applied in accordance with nameplate specifications. Bodine motors and gearmotors purchased with and used only with appropriately applied Bodine controls are covered by this warranty for a period of 24 months from the date of purchase or 30 months from date of manufacture, whichever comes first. Bodine motors and gearmotors used with non-Bodine controls and Bodine controls used with non-Bodine motors and gearmotors are covered by a 12 month warranty period. The Bodine Electric Company will repair, replace, or refund at its option, any of its products which has been found to be defective and within the warranty period, provided that the product is shipped freight prepaid, with previous authorization, to Bodine or to a Bodine Authorized Service Center. Bodine is not responsible for removal, installation, or any other incidental expenses incurred in shipping the products to or from Bodine. This warranty is in lieu of any other expressed or implied warranty – including, but not limited to, any implied warranties of merchantability and/or fitness for a particular use. Bodine's liability under this warranty shall be limited to repair or replacement of the Bodine product and Bodine shall not be liable, under any circumstances, for any consequential, incidental or indirect damages or expenses associated with the warranted products. Proof of purchase of motor or gearmotor and matching control as a system must be provided with any claim.

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However, the manufacturer retains the right to make changes in design,
which may not be included herein.**

