

Universal Robots for 2200 Series Conveyors

Service Manual



For other service manuals visit our website at: www.dornerconveyors.com/manuals-literature

Record Conveyor Serial Number Here

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Introduction

Dorner Mfg. Corp. has worked directly with Universal Robots to develop software to control 2200 Series conveyors using the Universal Robot controller. The UR controller requires the installation of a software file referred to as URCap. URCap makes the integration of Dorner conveyors easier for customers to setup configure and control. The Dorner conveyor URCap can be downloaded from our website, https://www.dornerconveyors.com/dorner-ursolutions.

Once installed in the UR controller, the conveyors can be added to the control program being created and allow the user to program the inputs and outputs needed for starting, stopping, speed reference, and status information (see **Figure 1**).

The Dorner URCap has been designed for both CB series and e-series controllers.

Programming for the variable speed drive should be done using the Frequency Inverter Operating Instructions manual.

Robot programming manual will be supplied with robot or can be found at the Universal Robots site https://www.universal-robots.com/.

Dorner Conveyor					
		elect the conveyor the conveyor cont			1.
Conveyo	or #1 ENAB	BLED	Conveyo	or #2 ENAB	BLED
Inputs		1	Inputs		
Faulted	config_in[7]		Faulted	Select 🗸 🗸	
At Speed	digital_in[6] 🛛 🔻			Select 🗸 🗸	
Load	analog_in[1] 🛛 🔻	Voltage 🗸 🔻	Load	Select 🗸 🗸	_
Outputs Forward(Run) Reverse Clear Fault	digital_out[7] digital_out[6] config_out[5]	🔄 Run Required	Outputs Forward(Run) Reverse Clear Fault	digital_out[0] digital_out[1] Select	🔲 Run Required
Conveyor Speed	analog_out[1] 🛛 🔻	Voltage 🗸 🗸	Conveyor Speed	analog_out[0] 🛛 🔻	Voltage 🔻
Conveyer Rate Enter the conveyors m (100%) speed in millin second		75	Conveyer Rate Enter the conveyors m (100%) speed in millin second		150

Figure 1

Warnings – General Safety



Dorner URCap Setup and Installation

Setup and Installation

- 1. Download Dorner URCap from https://www.dornerconveyors.com/dorner-ursolutions.
- 2. Load file DornerConveyor-1.x.x.urcap onto a memory stick.
- 3. Plug memory stick into USB port on Universal Controller teach pendant (see Figure 2).

File		02:02:42 CCCC 🕜
Program Installation Hove Tool		Feature View Tool Position X -120.11 mm Y -431.76 mm Z -253.53 mm
	Move Joints Base Shoulder	Nome
G simulation neal flabet	Wrist 2 Wrist 2 Wrist 2 Speed	46.29 * 91.39 • -1.78 • X Cancel ✓ OK

Figure 2

- 4. Follow URCap installation process in the Setup Robot section of programming:
 - a. Click the + button to install the Dorner URCap. Click the button to uninstall.
 - b. Select the DornerConveyor-1.x.x.urcap file and click open
 - c. The URCap will be opened and returned to the setup screen
 - d. When installing or uninstalling a URCap, a restart is required. Press Restart.
- 5. The URCap is now installed.

Status of the URCap in the setup screen:

Symbol	Meaning
1	URCap ok: Installed and running
\checkmark	
2	URCap fault: The URCap is installed but unable to start. Contact Dorner Mfg. Corp.
3	URCap restart needed: The URCap has been installed and needs to be restarted
C	

The installation is capable of controlling 1 or 2 Dorner conveyors. Enable each conveyor to be used, configure the inputs and outputs that will be used to control the variable frequency drive, and the scaling for the speed reference.

Installation Node

Enable the conveyors for use:

• Enable conveyor 1 and/or conveyor 2 to be used with the Universal Robot (see Figure 3).

Dorner Conveyor					
		elect the conveyor the conveyor cont			1.
Conveyo	or #1 ENAB	BLED	Conveyo	or #2 ENAB	BLED
Inputs		1	Inputs		1
Faulted	config_in[7]		Faulted	Select 🔹	
At Speed	digital_in[6] 🛛 🕶			Select 🗸 🗸	
Load	analog_in[1] 🛛 🔻	Voltage 🗸 🗸	Load	Select 🗸 🗸	•
				9 2	
Outputs			Outputs		
Forward(Run)	digital_out[7] 🛛 🔻	🗹 Run Required	Forward(Run)	digital_out[0] 🛛 🔻	🔲 Run Required
Reverse	digital_out[6] 🛛 🔻		Reverse	digital_out[1] 🛛 🔻	
Clear Fault	config_out[5] 🛛 🔻		Clear Fault	Select 🗸 🗸	
Conveyor Speed	analog_out[1] 🛛 🔻	Voltage 🛛 🔻	Conveyor Speed	analog_out[0] 🛛 🔻	Voltage 🛛 🔻
Conveyer Rate Enter the conveyors m (100%) speed in millin second		75	Conveyer Rate Enter the conveyors m (100%) speed in millin second		150

Figure 3

Inputs

Configure the inputs that the controller will receive from the variable frequency drive. These inputs are application dependant:

- Faulted input to the controller from the VFD signaling that it has faulted
- At Speed input is configurable to controller from the VFD signaling a status programmed in the VFD using the relay output
- Load input is an analog signal from the drive for the amount of load. This can be torque or current where 0-100% will equal 0-10V or 0(4)-20mA

Outputs

Configure the outputs that the controller will send to the VFD:

- Forward (Run) output to the VFD signaling it to start/run
- Reverse output to the VFD signaling it to run reverse
- Clear fault output to the VFD signaling it to clear a fault on the VFD when present
- **Conveyor Speed** analog output that can be configured for 0-10V DC or 0(4)-20mA as the speed reference for controlling the speed of the conveyor motor
- Conveyor Rate is used for scaling the speed reference and should be the conveyors maximum speed in millimetres per second
- Run Required Check Box this check box is used when both the Start/Run and the Reverse signals are required at the same time in order for the VFD to control the motor in the reverse direction

Programming Conveyor Nodes

When adding the conveyors to the program structure, the following window allows the user to program which conveyor needs to be inserted into the logic at that point. Select **Conveyor #1** or **Conveyor #2** and the desired control for the VFD.

NOTE: This is an empty program node - not set up yet (see Figure 4).

1	Dorner Conveyor		
		nveyor to run th target conveyo	ne direction. or speed [% max]:
	O Conveyor #1	Run	Forward
Ð	Conveyor #2	Stop	Reverse
	•	to target speed as % of full	



NOTE: This is a completed program and program node (see **Figure 5**). Highlighted program node is displayed in right side of image. Text in program node identifies the action to be performed.

> Basic		Q	Command	Graphics	Variables	
 > Advanced > Templates 	Robot Program Conveyor :1,Fwd,54 Conveyor :2,Rev,64		Dorner Co	onveyor		
VURCaps Dorner Conveyor	Conveyor :1,Stop					the direction. or speed [% max]:
			O Con	veyor #1	Run	Forward
	8)	(F	() Con	veyor #2	Stop	Reverse
				Slide to	target speed as % of f	ull speed.
			Speed 40.5 mm			
	★↓ 5 ♂ x ! 🖻	i a				



Universal Robots for 2200 Series Conveyors

Toolbar

In the e-series controller, a toolbar for Dorner conveyors is available at the top of the screen (see Figure 6).



Figure 6

When pressed, the toolbar brings up the Dorner conveyor status page that allows the user to see the fault status, speed, load, and if needed, jog the motor in a forward or reverse direction (see Figure 7).

Dorner -	Conveyor
Conveyor #1	Conveyor #2
FAULT	FAULT
RESET	
	cators
Conveyor #1	Conveyor #2
At Speed	
LOAD 0.0 %	LOAD %
L	
	og
Conveyor #1	Conveyor #2
Speed 50 %	Speed 50 %
Jog Fwd Jog Rev	Jog Fwd Jog Rev

Figure 7

NOTE:

- 1. Fault & fault reset are available, as they are configured in the installation tab.
- 2. Option "At Speed" is set up by choosing what output is configured from the VFD to the controller.
- 3. Load displays percent of load configured by terminal 30 and P150 in the VFD.
- 4. Jog section is only enabled when the program is not running. Conveyors will move at the speed selected as long as the button is pressed.

For Universal Robots with CB series controllers, the loading, programming and control are the same as the e-series. The screens may look different due to the screen size difference. The CB series does not have the Dorner URCap toolbar functionality (see **Figure 8**).

Here is w			or and setu ntrol comm				
Conveyor	#1 EN	ABLED	Conve	yor #2	EN.	ABLED	٦
Inputs	_		Inputs				
Faulted	digital_in[7] 🔻]	Faulted	Select	-]	
At Speed	digital_in[6] 🔻]	Enter	Select	-		
Load	analog_in[1] 🔻	Voltage •	Load	Select	-		•
Outputs Forward(Run) Reverse Clear Fault	digital_out[7] V digital_out[6] V digital_out[5] V	🖌 Run Requi.	Outputs Forward(R: Reverse Clear Fau	digital_out[1] 🔜 Run Req	[ui
Conveyor Speed	analog_out 🔻	Voltage	Conveyor S	eed analog_out	-	Voltage	
Conveyer Rate Enter the conve maximum (100% in millimeters p second) speed	75	Conveyer Ra Enter the c maximum (in millimeta second	onveyors 100%) speed		150	

Figure 8

NOTE: This is an empty program node - not set up yet (see Figure 9).

	onveyor to run t e target conveyo	he direction. or speed [% max]:
Conveyor #1	Run	Forward
Conveyor #2	Stop	Reverse
_	Slide to target speed as % of full	speed.
0 20 eed .0 mm/s	40 60	80 100

Figure 9

NOTE: This is a completed program and program node. Highlighted program node is displayed in right side of image. Text in program node identifies the action to be performed (see Figure 10).

	nveyor to run th target conveyo	
Conveyor #1	Run	Forward
O Conveyor #2	Stop	Reverse
s	ble to target speed as % of full sp	peel
o 20 Speed 40.5 mm/r	40 60	80 100

Figure 10

Dorner Full Feature Variable Frequency Drive

Variable Speed Controllers



Part Number	Input Volts	Input Phase	Input Hz	Output Volts	Output Phase	Max Hp	Output Amps*	Reversing
32MV1122(0)	115	1	60	230	3	0.5	2.2	Yes
32MV2122(0)	230	1	60	230	3	0.5	2.2	Yes
32MV1121(0)	115	1	60	230	3	1.0	4.0	Yes
32MV2121(0)	230	1	60	230	3	1.0	4.0	Yes
32MV2127(0)	230	1	60	230	3	2.0	6.8	Yes
32MV2322(0)	230	3	60	230	3	0.5	2.2	Yes
32MV2327(0)	230	3	60	230	3	2.0	6.8	Yes
32MV4341(0)	460	3	60	460	3	1.0	2.0	Yes
32MV4347(0)	460	3	60	460	3	2.0	3.4	Yes

(0) = Optional M12 Accessory Port No Option = No Accessory Port E = M12 Port wired for End Stop Photo Eye Application I = M12 port wired for Index Photo Eye Application Note: E or I options will work with Dorner Control Stop or Jog Button Accessories

Figure 11

Drive Programming

Parameters:

P100	1 Terminal Strip Control
P101	1 - 10V DC
P112	1 Fwd/Rev
P121	10 Reverse Rotation
P122	20 Clear Fault
P140	4 Inverse Fault
P142	6 At Speed
P150	1 - 10V DC Load

NOTE: This is an example. Inputs, outputs, and programming can be changed based on application.



Figure 12



Wiring Diagram

Wiring Examples

Wiring Examples

Dorner Full Feature Variable Frequency Drive European Version

Frequency Converter

Chart A	Variable Speed Frequency Converter, Full CE Compliance								
 Adjustable Speed, 2 IP 54 Enclosure Digital Device Adjustable Start and Adjustable timing ge Control by external se Integrated motor pro- Includes standard place 	l Stop enerator built in signals via free in otection						Regulatory Approvals		
		Input							
		Inp	out			Output			
Part Number	Volts	Inp Phase	ut Hz	Watts	Volts	Phase	Watts		
Part Number KT103342	Volts 230			Watts 250	Volts 230	and the second	Watts 90		
			Hz			Phase			

Figure 14

DC1 Variable Frequency Drive







Drive Programming

Parameters:

P-12	0 Control Signal Terminals
P-15	8 DI1 Start, DI2 Fwd/Rev
P-16	0 - 10V DC
P-18	3 Error Message (Not Ready)
P-25	9 Output Current

NOTE: This is an example. Inputs, outputs, and programming can be changed based on application.

Wiring Diagram



Figure 16

Universal Robots for 2200 Series Conveyors

Wiring Examples

Return Policy

Returns must have prior written factory authorization or they will not be accepted. Items that are returned to Dorner without authorization will not be credited nor returned to the original sender. When calling for authorization, please have the following information ready for the Dorner factory representative or your local distributor:

- 1. Name and address of customer.
- 2. Dorner part number(s) of item(s) being returned.
- 3. Reason for return.
- 4. Customer's original order number used when ordering the item(s).
- 5. Dorner or distributor invoice number. Include part serial number if available.

A representative will discuss action to be taken on the returned items and provide a Returned Materials Authorization (RMA) number for reference. RMA will automatically close 30 days after being issued. To get credit, items must be new and undamaged. There will be a return charge on all items returned for credit, where Dorner was not at fault. It is the customer's responsibility to prevent damage during return shipping. Damaged or modified items will not be accepted. The customer is responsible for return freight.

	Product Type								
	Standard Products							Engineered to order parts	
Product Line	Conveyors	Gearmotors & Mounting Packages	Support Stands	Accessories	Spare Parts (non-belt)	Spare Belts - Standard Flat Fabric	Spare Belts - Cleated & Spec. Fabric	Spare Belts - Plastic Chain	All equipment and parts
1100 Series				•		•			
2200 Series	30% return fee for all products except:								
3200 Series	50% return fee for conveyors with modular belt,								
Pallet Systems	cleated belt or speciality belts								
FlexMove/SmartFlex	<u>-</u> .								
GAL Series	All Electr	All Electrical items are assigned original manufacturers return policy.						non-returnable	
All Electrical		Tion-returnable							case-by-case
7100 Series									
7200/7300 Series									
AquaGard 7350 Series Version 2	50% return fee for all products								
GES Series	1								
AquaGard 7350/7360 Series	non-returnable						•		
AquaPruf Series									

Returns will not be accepted after 60 days from original invoice date. The return charge covers inspection, cleaning, disassembly, disposal and reissuing of components to inventory. If a replacement is needed prior to evaluation of returned item, a purchase order must be issued. Credit (if any) is issued only after return and evaluation is complete.

Dorner has representatives throughout the world. Contact Dorner for the name of your local representative. Our Customer Service Team will gladly help with your questions on Dorner products.

For a copy of Dorner's Warranty, contact Dorner, an authorized sales channel or visit our website: www.dorner.com.

For replacement parts, contact an authorized Dorner Service Center or the factory.

www.dorner.com





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