

# Universal Robots for 2200 Series Conveyors

**Service Manual** 



For other service manuals visit our website at: www.dornerconveyors.com/manuals-literature

**Record Conveyor Serial Number Here** 

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### Introduction

Dorner Mfg. Corp. has worked directly with Universal Robots to develop software to control 2200 Series conveyors using the Universal Robot controller. The UR controller requires the installation of a software file referred to as URCap. URCap makes the integration of Dorner conveyors easier for customers to setup configure and control. The Dorner conveyor URCap can be downloaded from our website, https://www.dornerconveyors.com/dorner-ursolutions.

Once installed in the UR controller, the conveyors can be added to the control program being created and allow the user to program the inputs and outputs needed for starting, stopping, speed reference, and status information (see **Figure 1**).

The Dorner URCap has been designed for both CB series and e-series controllers.

Programming for the variable speed drive should be done using the Frequency Inverter Operating Instructions manual.

Robot programming manual will be supplied with robot or can be found at the Universal Robots site https://www.universal-robots.com/.

Dorner Conveyor								
	This is used to select the conveyor and setup the action and direction. Here is where the conveyor control communication is established							
Conveyo	or #1 ENAE	BLED	Conveyo	or #2 ENAB	BLED			
Inputs			Inputs					
Faulted	config_in[7]		Faulted	Select 🗸 🗸				
At Speed	digital_in[6] 🛛 🔻			Select 🗸 🗸				
Load	analog_in[1] 🛛 🔻	Voltage 🔻	Load	Select 🗸 🗸	<b>_</b>			
Outputs Forward(Run) Reverse Clear Fault	digital_out[7] digital_out[8] config out[5]	🕤 Run Required	Outputs Forward(Run) Reverse Clear Fault	digital_out[0] digital_out[1] Select	Run Required			
Conveyor Speed	analog_out[1] 🔻	Voltage 🔻	Conveyor Speed	analog_out[0] 🔻	Voltage 🗸			
Conveyer Rate Enter the conveyors m (100%) speed in millim second	naximum neters per	75	Conveyer Rate Enter the conveyors m (100%) speed in millim second	naximum neters per	150			

Figure 1

# Warnings – General Safety



### **Dorner URCap Setup and Installation**

### **Setup and Installation**

- 1. Download Dorner URCap from https://www.dornerconveyors.com/dorner-ursolutions.
- 2. Load file DornerConveyor-1.x.x.urcap onto a memory stick.
- 3. Plug memory stick into USB port on Universal Controller teach pendant (see Figure 2).

File		02:02:42 CCCC 🕜
Hove Tool	Here to top	Feature View  Tool Position X -120.11 mm Y -431.76 mm Z -253.53 mm
	Heve Joints Base Shoulder	Nome 
G Simulation neul Robot	seed Oloos	46.29 * 91.39 * 1.78 * ★ Cancel ✔ OK

#### Figure 2

- 4. Follow URCap installation process in the Setup Robot section of programming:
  - a. Click the + button to install the Dorner URCap. Click the button to uninstall.
  - b. Select the DornerConveyor-1.x.x.urcap file and click open
  - c. The URCap will be opened and returned to the setup screen
  - d. When installing or uninstalling a URCap, a restart is required. Press Restart.
- 5. The URCap is now installed.

Status of the URCap in the setup screen:

Symbol	Meaning
1	URCap ok: Installed and running
$\bigcirc$	
2	URCap fault: The URCap is installed but unable to start. Contact Dorner Mfg. Corp.
3	URCap restart needed: The URCap has been installed and needs to be restarted
S	

The installation is capable of controlling 1 or 2 Dorner conveyors. Enable each conveyor to be used, configure the inputs and outputs that will be used to control the variable frequency drive, and the scaling for the speed reference.

### Installation Node

Enable the conveyors for use:

• Enable conveyor 1 and/or conveyor 2 to be used with the Universal Robot (see Figure 3).

Dorner Conveyor							
	This is used to select the conveyor and setup the action and direction. Here is where the conveyor control communication is established						
Conveyo	or #1 ENAB	BLED	Conveyo	or #2 ENAB	BLED		
Inputs		1	Inputs		1		
Faulted	config_in[7]		Faulted	Select 🔹			
At Speed	digital_in[6] 🛛 🕶			Select 🗸 🗸			
Load	analog_in[1] 🛛 🔻	Voltage 🗸 🗸	Load	Select 🗸 🗸	<b>•</b>		
				9 <del>2</del>			
Outputs			Outputs				
Forward(Run)	digital_out[7] 🛛 🔻	🗹 Run Required	Forward(Run)	digital_out[0] 🛛 🔻	🔲 Run Required		
Reverse	digital_out[6] 🛛 🔻		Reverse	digital_out[1] 🛛 🔻			
Clear Fault	config_out[5] 🛛 🔻		Clear Fault	Select 🗸 🗸			
Conveyor Speed	analog_out[1] 🛛 🔻	Voltage 🛛 🔻	Conveyor Speed	analog_out[0] 🛛 🔻	Voltage 🛛 🔻		
Conveyer Rate Enter the conveyors m (100%) speed in millin second	naximum neters per	75	Conveyer Rate Enter the conveyors m (100%) speed in millin second	naximum neters per	150		

Figure 3

#### Inputs

Configure the inputs that the controller will receive from the variable frequency drive. These inputs are application dependant:

- Faulted input to the controller from the VFD signaling that it has faulted
- At Speed input is configurable to controller from the VFD signaling a status programmed in the VFD using the relay output
- Load input is an analog signal from the drive for the amount of load. This can be torque or current where 0-100% will equal 0-10V or 0(4)-20mA

#### Outputs

Configure the outputs that the controller will send to the VFD:

- Forward (Run) output to the VFD signaling it to start/run
- Reverse output to the VFD signaling it to run reverse
- Clear fault output to the VFD signaling it to clear a fault on the VFD when present
- **Conveyor Speed** analog output that can be configured for 0-10V DC or 0(4)-20mA as the speed reference for controlling the speed of the conveyor motor
- Conveyor Rate is used for scaling the speed reference and should be the conveyors maximum speed in millimetres per second
- Run Required Check Box this check box is used when both the Start/Run and the Reverse signals are required at the same time in order for the VFD to control the motor in the reverse direction

#### **Programming Conveyor Nodes**

When adding the conveyors to the program structure, the following window allows the user to program which conveyor needs to be inserted into the logic at that point. Select **Conveyor #1** or **Conveyor #2** and the desired control for the VFD.

NOTE: This is an empty program node - not set up yet (see Figure 4).

1	Dorner Conveyor		
	Set the cor Then select the	nveyor to run th target conveyo	ne direction. or speed [% max]:
	O Conveyor #1	Run	Forward
Ð	Conveyor #2	Stop	Reverse
	Slide	to target speed as % of full	I speed.



NOTE: This is a completed program and program node (see **Figure 5**). Highlighted program node is displayed in right side of image. Text in program node identifies the action to be performed.

> Basic		Q	Command	Graphics	Variables	
<ul> <li>&gt; Advanced</li> <li>&gt; Templates</li> </ul>	<ul> <li>Robot Program</li> <li>Conveyor :1,Fwd,54</li> <li>Conveyor :2,Rev.64</li> </ul>		Dorner Co	onveyor		
VIRCaps Dorner Conveyor	Conveyor :1,Stop		Se Then se	et the conv elect the ta	reyor to run arget convey	the direction. or speed [% max]:
			O Con	veyor #1	Run	Forward
	8)	(F	O Con	veyor #2	Stop	Reverse
				Slide to	target speed as % of f	ull speed.
			Speed 40.5 mm	v 20 Vs		
	<b>★↓</b> う ぐ X 連 団	<b>i a</b>				



Universal Robots for 2200 Series Conveyors

### Toolbar

In the e-series controller, a toolbar for Dorner conveyors is available at the top of the screen (see Figure 6).



#### Figure 6

When pressed, the toolbar brings up the Dorner conveyor status page that allows the user to see the fault status, speed, load, and if needed, jog the motor in a forward or reverse direction (see Figure 7).

Dorner -	Conveyor
Conveyor #1	Conveyor #2
FAULT	FAULT
RESET	
Indic	cators
Conveyor #1	Conveyor #2
At Speed	
1040 0.0%	LOAD %
LOAD 0.0 %	LOAD 70
L	
Conveyor #1	Conveyor #2
Streed 50 %	Speed E0 %
Speed 50 %	Speed 50 %
log Ewd log Rev	log Fwd log Bey
Jograd	Jog I wa Jog Kev
<u></u>	L

Figure 7

#### NOTE:

- 1. Fault & fault reset are available, as they are configured in the installation tab.
- 2. Option "At Speed" is set up by choosing what output is configured from the VFD to the controller.
- 3. Load displays percent of load configured by terminal 30 and P150 in the VFD.
- 4. Jog section is only enabled when the program is not running. Conveyors will move at the speed selected as long as the button is pressed.

For Universal Robots with CB series controllers, the loading, programming and control are the same as the e-series. The screens may look different due to the screen size difference. The CB series does not have the Dorner URCap toolbar functionality (see **Figure 8**).

	nere the c	onveyor cont	rol commun	ication is	e:	stablishe	d
Conveyor	r #1 EN	ABLED	Conveyor	· #2 E	N	ABLED	٦
Inputs	-		Inputs		_	2	
Faulted	digital_in[7]	•	Faulted	Select	•	]	
At Speed	digital_in[6]	•	Enter	Select	-	]	
Load	analog_in[1]	Voltage 🔻	Load	Select	-		-
Reverse Clear Fault	digital_out[6]	Kun Kequ	Reverse Clear Fault	digital_out[1] Select	•	Kun Keq	u
Conveyor Speed	analog_out	🗸 Voltage 🗸 👻	Conveyor Speed	analog_out	-	Voltage	
Conveyer Rate Enter the conve maximum (100% in millimeters p	eyors 6) speed er	75	Conveyer Rate Enter the conve maximum (100% in millimeters p	eyors 6) speed er	[	150	

Figure 8

NOTE: This is an empty program node - not set up yet (see Figure 9).

Set the c Then select th	onveyor to run the e target conveyor	e direction. speed [% max]:	
Conveyor #1	Run	Forward	
Conveyor #2	Stop	Reverse	
_	Slide to target speed as % of full sp	eed.	
0 20	40 60	80 100	

Figure 9

NOTE: This is a completed program and program node. Highlighted program node is displayed in right side of image. Text in program node identifies the action to be performed (see Figure 10).

Set the co Then select the	onveyor to run th e target conveyo	e direction. r speed [% ma
Conveyor #1	Run	Forward
O Conveyor #2	Stop	Reverse
3	lide to target speed as % of full s	peel
0 20 Speel 40.5 mm/s	40 60	80 100

Figure 10

### **Dorner Full Feature Variable Frequency Drive**

### Variable Speed Controllers



Part Number	Input Volts	Input Phase	Input Hz	Output Volts	Output Phase	Max Hp	Output Amps*	Reversin
32MV1122(0)	115	1	60	230	3	0.5	2.2	Yes
2MV2122(0)	230	1	60	230	3	0.5	2.2	Yes
32MV1121(0)	115	1	60	230	3	1.0	4.0	Yes
32MV2121(0)	230	1	60	230	3	1.0	4.0	Yes
32MV2127(0)	230	1	60	230	3	2.0	6.8	Yes
32MV2322(0)	230	3	60	230	3	0.5	2.2	Yes
32MV2327(0)	230	3	60	230	3	2.0	6.8	Yes
32MV4341(0)	460	3	60	460	3	1.0	2.0	Yes
32MV4347(0)	460	3	60	460	3	2.0	3.4	Yes

(0) = Optional M12 Accessory Port No Option = No Accessory Port E = M12 Port wired for End Stop Photo Eye Application I = M12 port wired for Index Photo Eye Application Note: E or I options will work with Dorner Control Stop or Jog Button Accessories

Figure 11

#### **Drive Programming**

Parameters:

P100	1 Terminal Strip Control
P101	1 - 10V DC
P112	1 Fwd/Rev
P121	10 Reverse Rotation
P122	20 Clear Fault
P140	4 Inverse Fault
P142	6 At Speed
P150	1 - 10V DC Load

NOTE: This is an example. Inputs, outputs, and programming can be changed based on application.



Figure 12



#### Wiring Diagram

### Wiring Examples

# Wiring Examples

### **Dorner Full Feature Variable Frequency Drive European Version**

### **Frequency Converter**

Chart A	Variable Speed Frequency Converter, Full CE Compliance								
<ul> <li>Adjustable Speed, 20 to 70 Hz</li> <li>IP 54 Enclosure</li> <li>Digital Device</li> <li>Adjustable Start and Stop</li> <li>Adjustable timing generator built in</li> <li>Control by external signals via free inputs</li> <li>Integrated motor protection</li> <li>Includes standard plug for 230V, 50 Hz, 1 Phase</li> </ul>									
	Input				Output				
Part Number	Volts	Phase	Hz	Watts	Volts	Phase	Watts		
KT103342	230	1	50	250	230	3	90		
KT200350	230	1	50	250	230	3	180		
KT103343	230	1	50	446	230	3	370		

Figure 14

DC1 Variable Frequency Drive







#### **Drive Programming**

Parameters:

P-12	0 Control Signal Terminals
P-15	8 DI1 Start, DI2 Fwd/Rev
P-16	0 - 10V DC
P-18	3 Error Message (Not Ready)
P-25	9 Output Current

NOTE: This is an example. Inputs, outputs, and programming can be changed based on application.

#### **Wiring Diagram**



Figure 16

#### Universal Robots for 2200 Series Conveyors

### Wiring Examples

# **Return Policy**

Returns must have prior written factory authorization or they will not be accepted. Items that are returned to Dorner without authorization will not be credited nor returned to the original sender. When calling for authorization, please have the following information ready for the Dorner factory representative or your local distributor:

- 1. Name and address of customer.
- 2. Dorner part number(s) of item(s) being returned.
- 3. Reason for return.
- 4. Customer's original order number used when ordering the item(s).
- 5. Dorner or distributor invoice number. Include part serial number if available.

A representative will discuss action to be taken on the returned items and provide a Returned Materials Authorization (RMA) number for reference. RMA will automatically close 30 days after being issued. To get credit, items must be new and undamaged. There will be a return charge on all items returned for credit, where Dorner was not at fault. It is the customer's responsibility to prevent damage during return shipping. Damaged or modified items will not be accepted. The customer is responsible for return freight.

	Product Type								
	Standard Products						Engineered to order parts		
Product Line	Conveyors	Gearmotors & Mounting Packages	Support Stands	Accessories	Spare Parts (non-belt)	Spare Belts - Standard Flat Fabric	Spare Belts - Cleated & Spec. Fabric	Spare Belts - Plastic Chain	All equipment and parts
1100 Series									
2200 Series	30% return fee for all products except: 50% return fee for conveyors with modular belt, cleated belt or speciality belts								
3200 Series									
Pallet Systems									
FlexMove/SmartFlex	All Electrical items are assigned original manufacturers return policy.								
GAL Series								case-by-case	
All Electrical									
7100 Series									
7200/7300 Series	1								
AquaGard 7350 Series Version 2	50% return fee for all products								
GES Series									
AquaGard 7350/7360 Series	non-returnable								
AquaPruf Series									

Returns will not be accepted after 60 days from original invoice date. The return charge covers inspection, cleaning, disassembly, disposal and reissuing of components to inventory. If a replacement is needed prior to evaluation of returned item, a purchase order must be issued. Credit (if any) is issued only after return and evaluation is complete.

Dorner has representatives throughout the world. Contact Dorner for the name of your local representative. Our Customer Service Team will gladly help with your questions on Dorner products.

For a copy of Dorner's Warranty, contact Dorner, an authorized sales channel or visit our website: www.dorner.com.

For replacement parts, contact an authorized Dorner Service Center or the factory.

# www.dorner.com





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